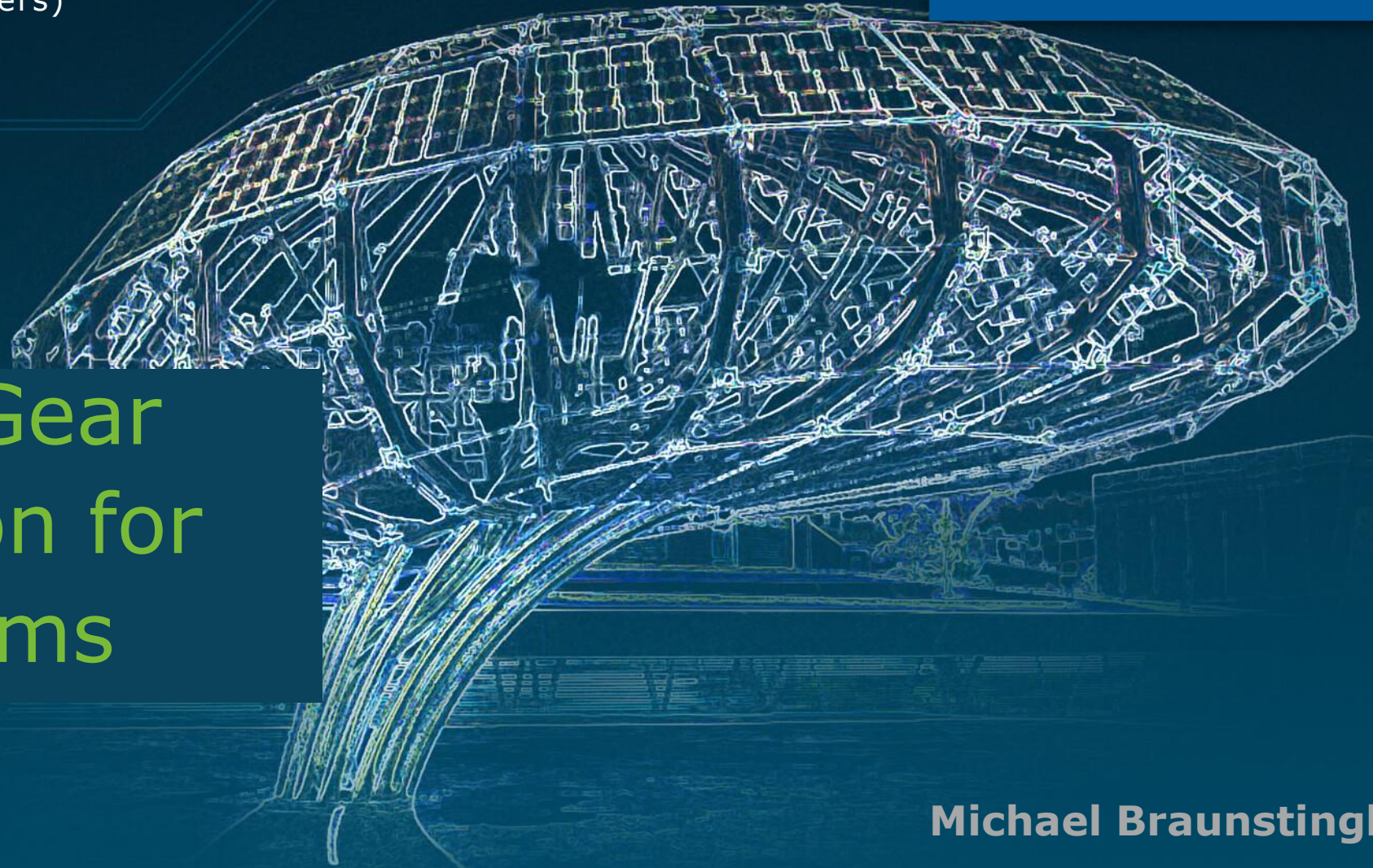


AVL List GmbH (Headquarters)

# Advanced Gear Optimization for AWD Systems



Michael Braunstingl

# Content

Introduction

## 1. Introduction

- Gears in AWD Systems
- Why is the hypoid gear so difficult to optimize?
- Optimization Method: "Design of Experiment" (DOE)
- Evaluation of DOE Results

Base Variant Analysis

## 2. Simulation Models

- Base Variant Analysis Workflow
- Assembly Static Simulation Model
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## 3. Gear Optimization Workflow

- General Description
- Can a single tool handle the entire optimization?
- Macro Geometry Optimization
- Micro Geometry Optimization

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Summary



# Introduction

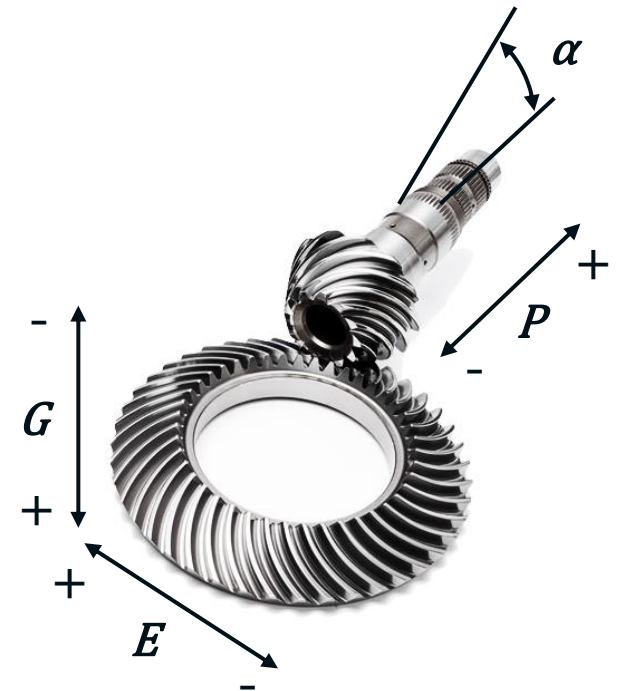
## Gears in AWD Systems

### Variable speed transmission with cylindrical gears

- Parameters well understood
- Analytical tooth contact equations
- Simple production process
- Stable contact pattern with increasing load

### Topic today: Differential transmission with hypoid gears

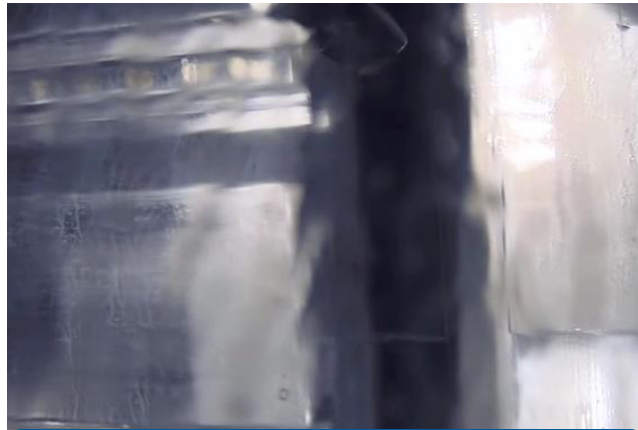
- Transfer very high loads
- Contact pattern varies with increasing load → "E, P, G, a"
- Tooth geometry defined by machine settings
- Complicated production processes
- Gear design based on "experience" with manual variation of parameters



# Introduction

Why is the hypoid gear so difficult to optimize?

## Cutting



Video: Hypoid Cutting (FH)

Define macro geometry

- Machine motion
- Cutter blade geometry (+ tolerances)

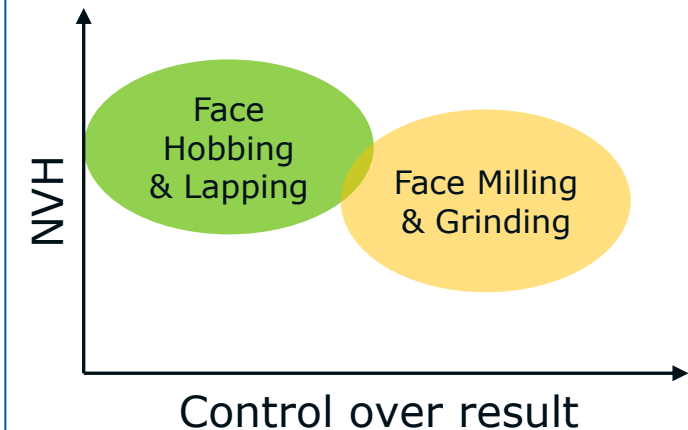
## Heat Treatment



Improve load carrying capacity

- Introduces geometrical distortions

## Lapping / Grinding



Define micro geometry

- Lapping as accelerated wear (non-deterministic)
- Better control over geometry with grinding

# Introduction

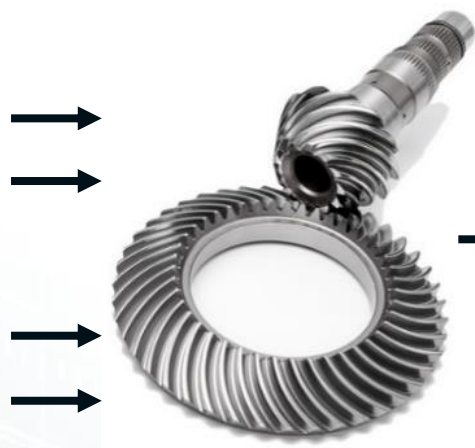
## Optimization Method: "Design of Experiment" (DOE)

*Extremum problem* ← Find the gear geometry variant that is robust against manufacturing tolerances, assembly errors, deflection

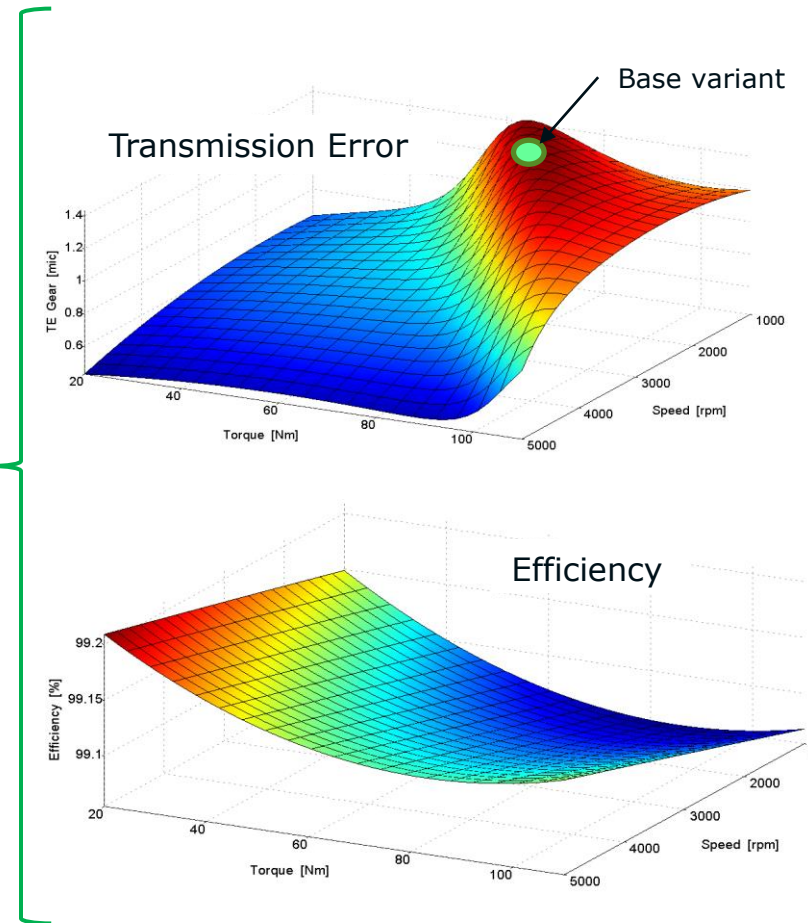
Input parameters → DOE variants → Hypersurface

- Geometry definition:**
- Pressure angle
  - Spiral angle
  - Cutter head diameter
  - Tooth height
  - Tooth root radius
  - ...

- Disturbance:**
- Assembly Errors
  - Manufacturing tolerances
  - Temperature, Load (EPGa)



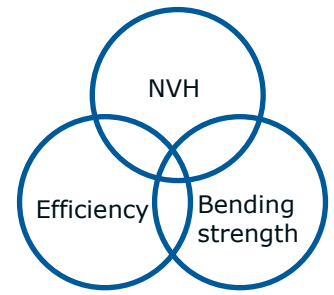
- Output:**
- TE, NVH
  - Efficiency
  - Life



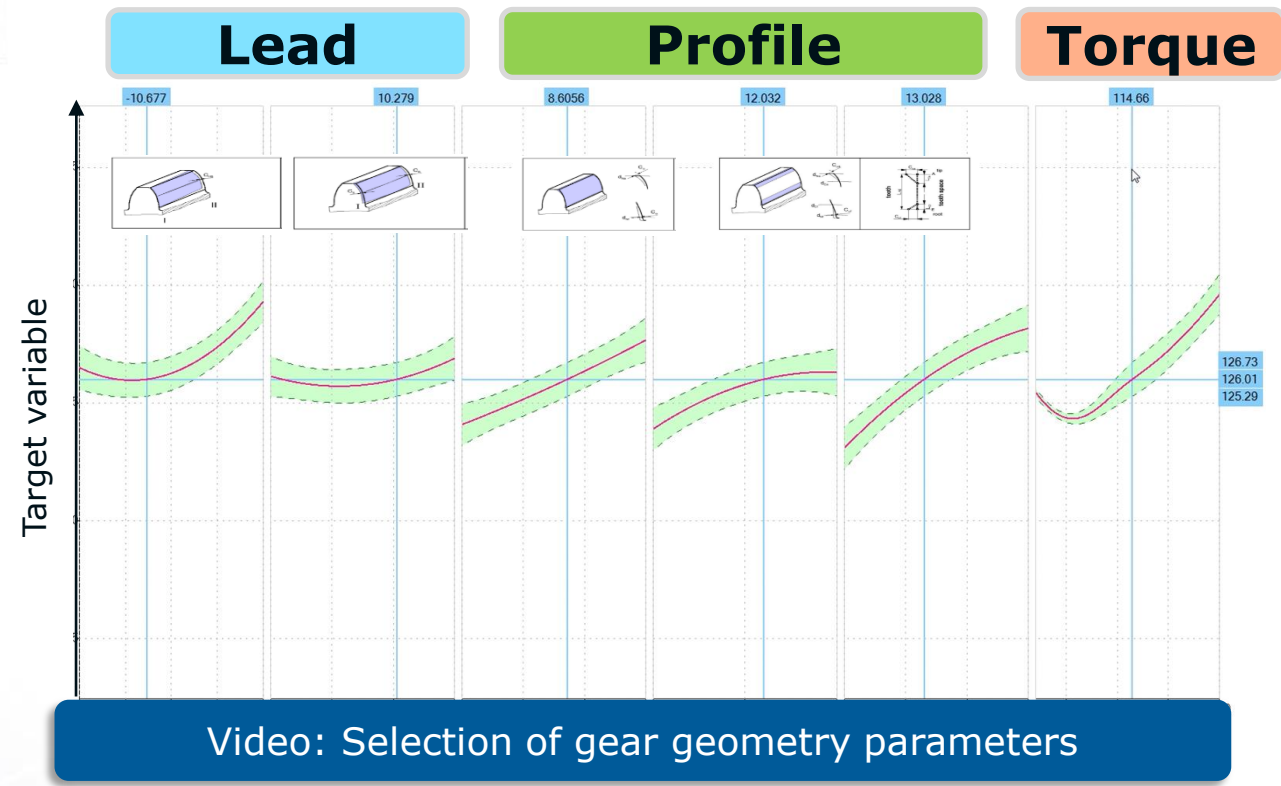
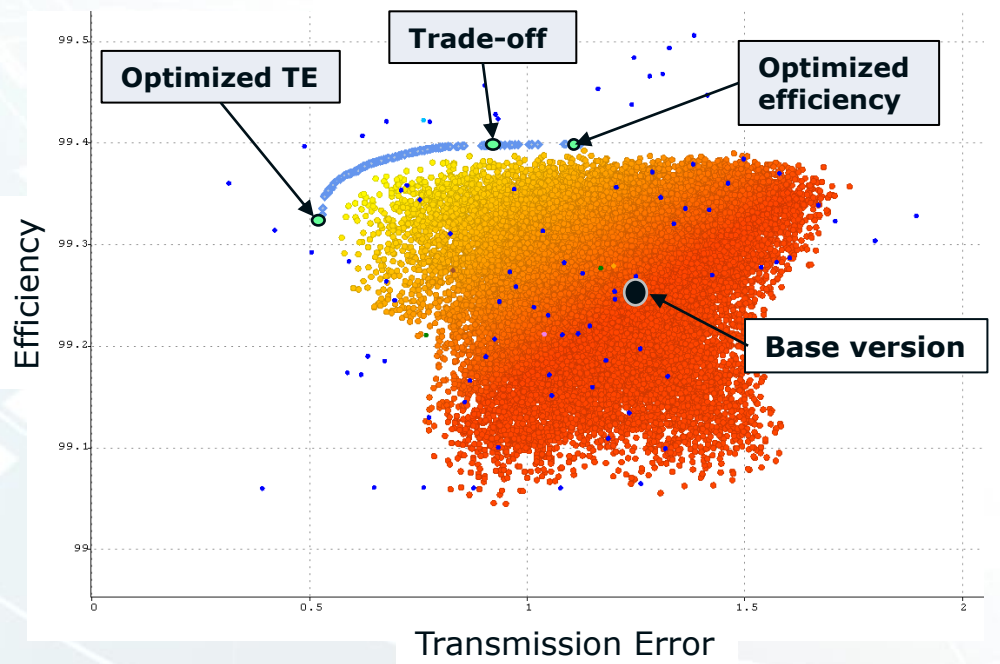
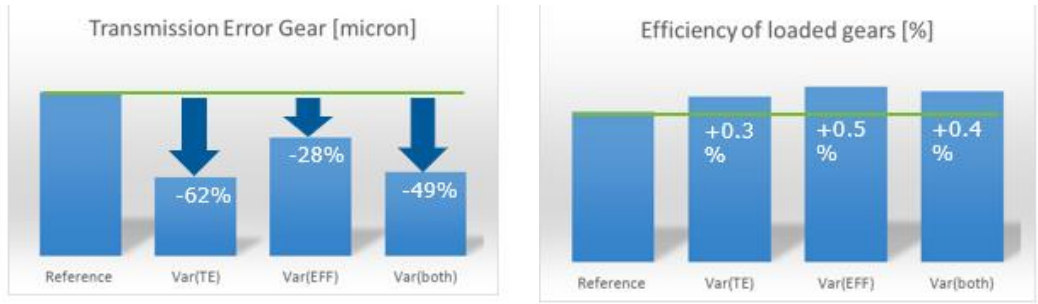
# Introduction

## Evaluation of DOE Results

AVL CAMEO



Introduction  
Base Variant Analysis  
Gear Optimization  
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Video: Selection of gear geometry parameters

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# Base Variant Analysis Workflow

Introduction  
 Base Variant Analysis  
 Gear Optimization  
 Validation  
 Summary

Load spectrum  
 Hypoid geometry (.spa file)

**Loaded TCA**  
Ansol CALYX

$f_i^{\text{th}}$  element

'Summarized mesh point' data

X/Y/Z-Location of Summarized Mesh Point	X/Y/Z-Direction of Line of Action	Kinematic Transmission Error (TE)	Meshing Stiffness

**Gear deflection**  
EPGa

@ certain loads  
 eg:  
 - 30 %  
 + 10 %  
 + 50 %  
 + 100 %

**Assembly Model**  
Abaqus FEA

Feedback loop

**Testbed Model: Dynamic MBS**  
AVL EXCITE

- Block based model
- Condensed FE bodies
- Joints for bearings, gears, bushings

Noise vibration and harshness (NVH)

- Dynamic TE
- Campbell plots
- Structure-borne and airborne noise

# Assembly Static Simulation Model

## Simulia Abaqus FEA

Introduction

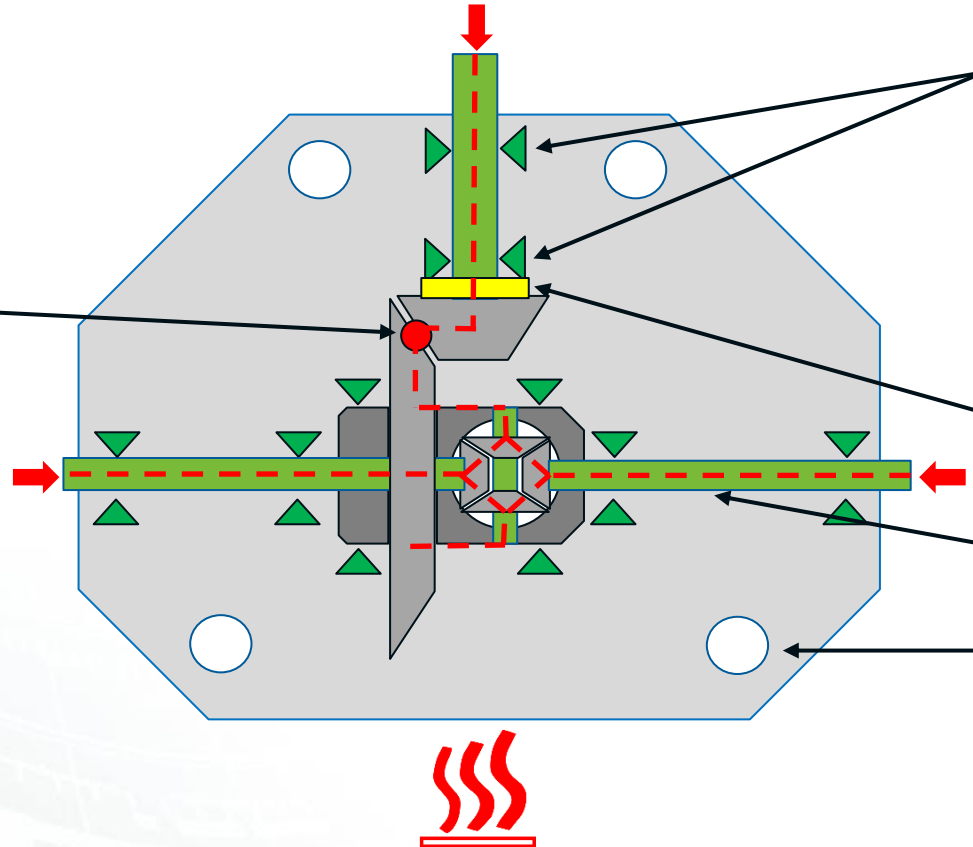
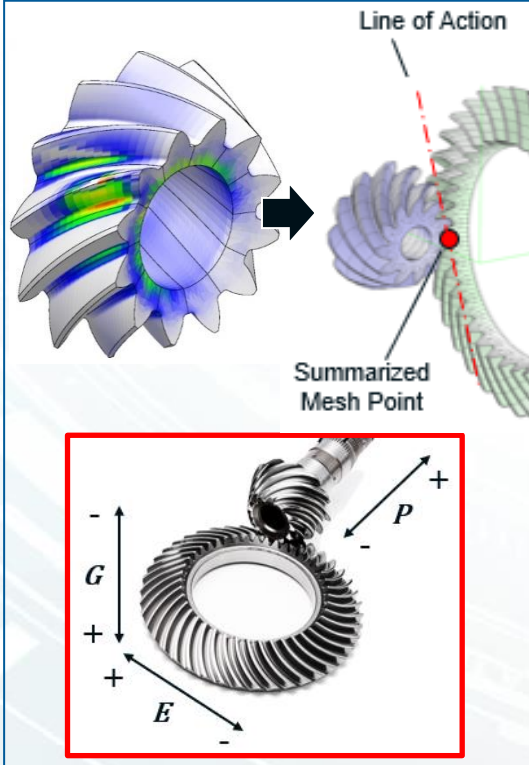
Base Variant Analysis

Gear Optimization

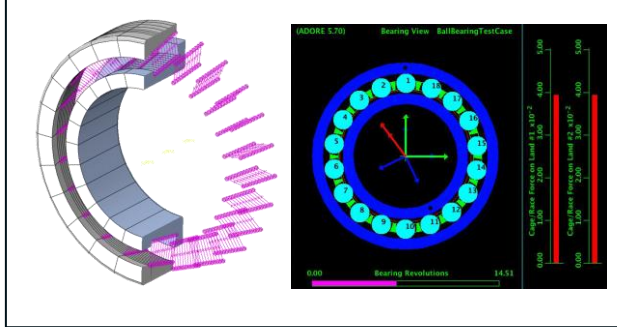
Validation

Summary

Hypoid gear contact modelling at 'summarized mesh point' supported by numerical TCA in Finite Element solver



Bearing stiffness modelling (preload, temperature, wear)



Plastic/elastic material properties (e.g. shims)

Shaft deflections

Housing with boundary conditions

- Constraints
- Bushings
- Thermal conditions



- Roller bearing
- Shaft
- Torque transfer path
- Bevel gear

# Assembly Dynamic Simulation Model

## AVL EXCITE



Introduction

AVL EXCITE is a block based multi body simulation tool using finite element flexible bodies

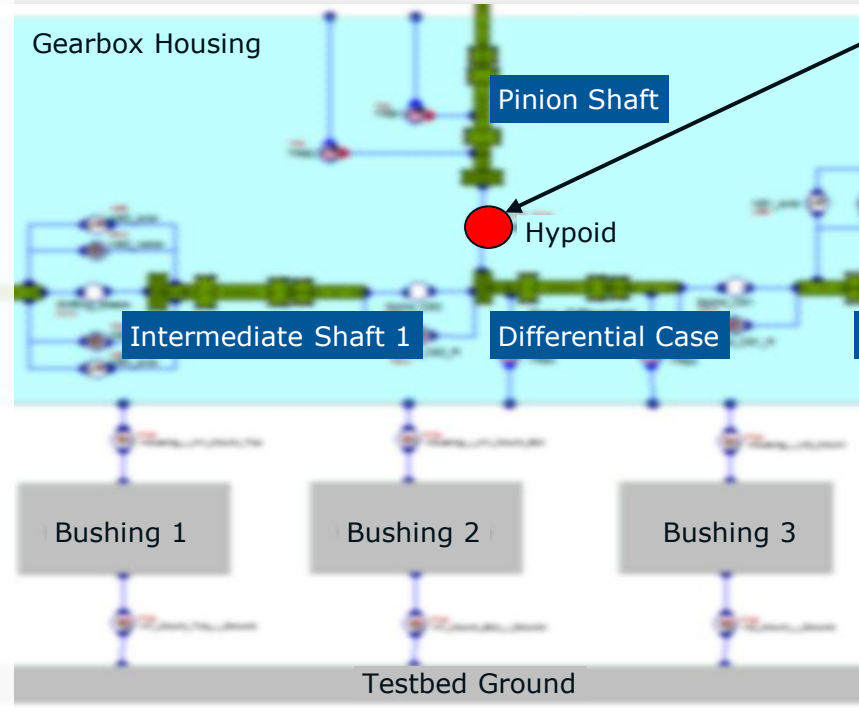
- Housing
- Shafts
- Rolling element bearings
- Flexible cylindrical gears (analytical solution)
- TCA joint (precalculated solution)

Base Variant Analysis

Gear Optimization

Validation

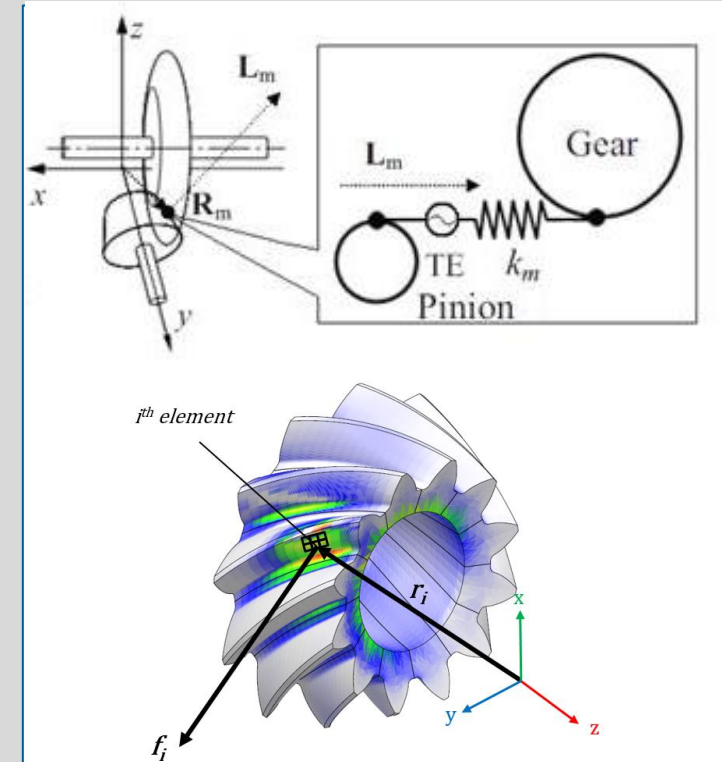
Summary



### SHYP\_TCA joint

Requires "summarized mesh point" data: location, force, kinematic TE, meshing stiffness

Mesh force and torque are applied onto the condensed centroid nodes of FE parts.



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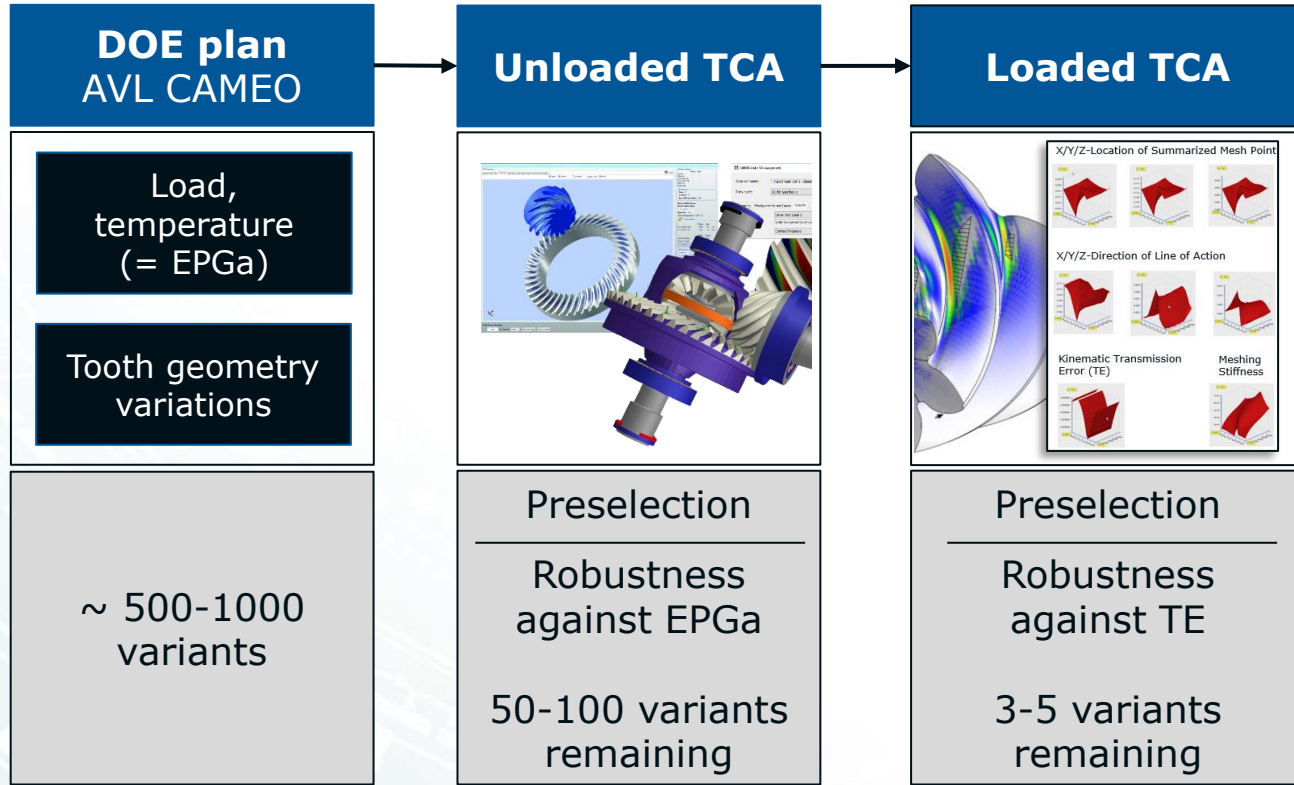
## 5. Summary and Outlook



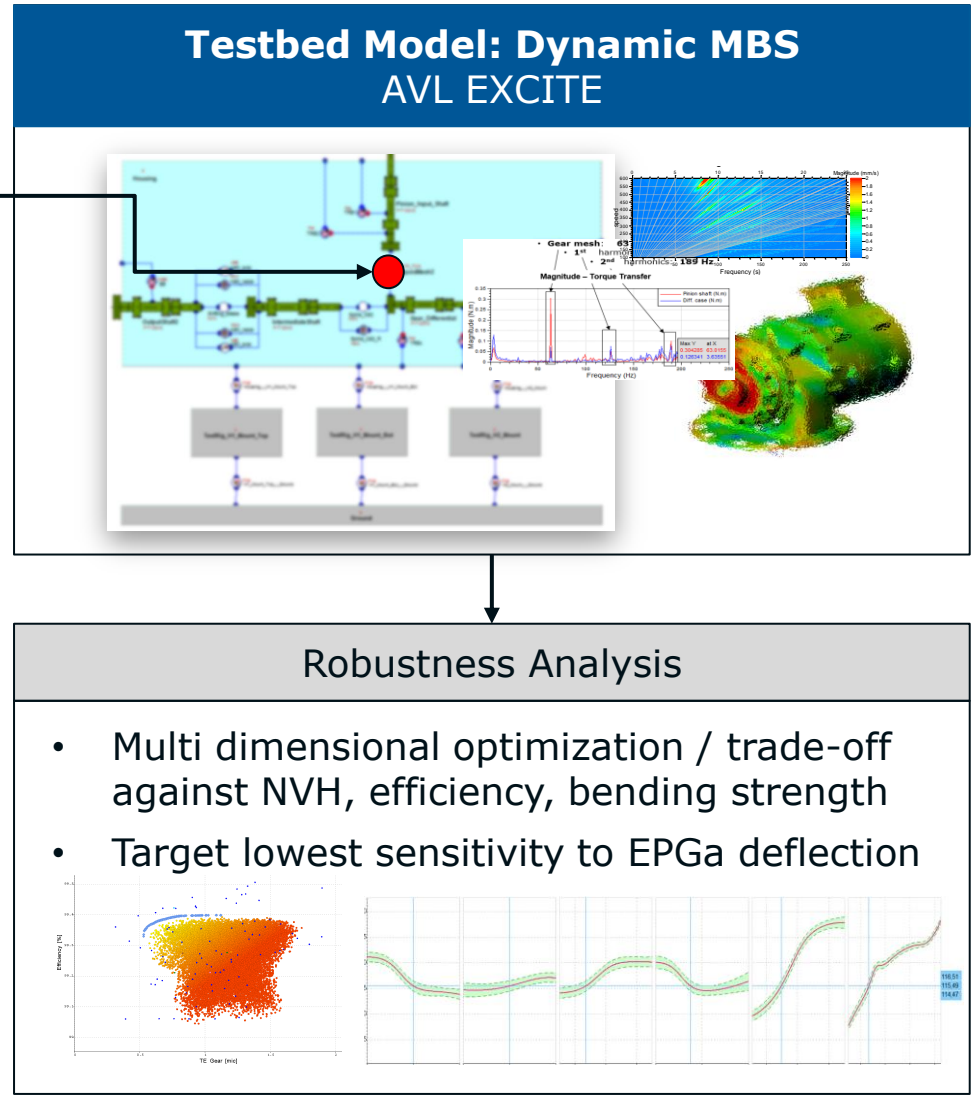
# Gear Optimization Workflow

## General Description

Introduction  
Base Variant Analysis  
Gear Optimization  
Validation  
Summary



**Resulting geometry must be manufacturable**



# Gear Optimization Workflow

Can a single tool handle the entire optimization?

## Commercially available gear design software

### Advantages:

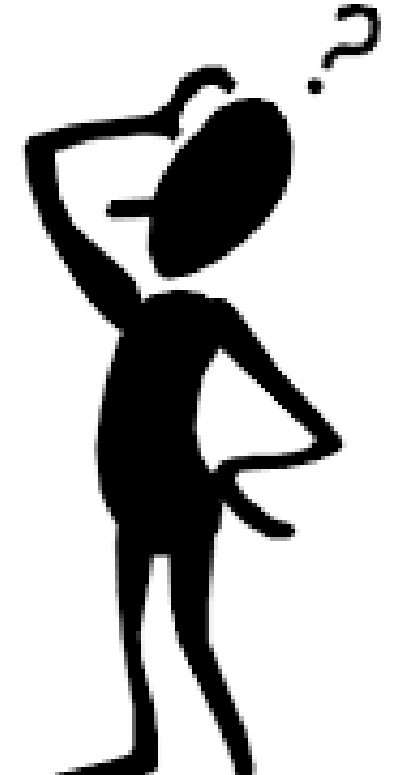
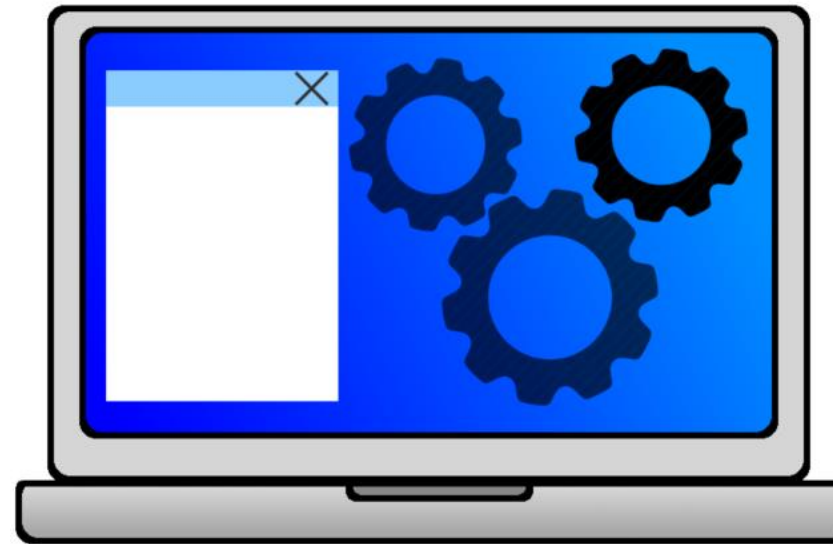
- Simple user interface
- Ease-off based optimization
- Quick response
- Manufacturability guaranteed

### Disadvantages:

- No automation possible
- No external access to LTCA results
- Impossible to perform the entire DOE process



Combination of tools necessary



# Gear Optimization Workflow

## Macro Geometry

Introduction  
Base Variant Analysis  
Gear Optimization  
Validation  
Summary

### Abaqus FEA

EPGa

### Unloaded TCA

.spa  
EPGa

### Loaded TCA

Look-up  
Tables

### Dynamics

From base variant:  
• EPGa variation space (load, temperature)

### DOE

Machine settings

Input:  
• 5-6 geometry parameters  
Tolerance study:  
• Variation of machine settings

#### Gleason GEMS

- Design of gear macro and micro geometry**
  - Consideration of manufacturing tolerances by applying deviations in machine settings
- Analysis of:**
  - Geometrical contact pattern (Ease-off based)
  - Kinematic transmission error
- Processing automation by hijacking KissSoft / GEMS interface**

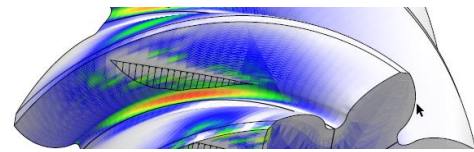


#### 4. Manufacturability guaranteed



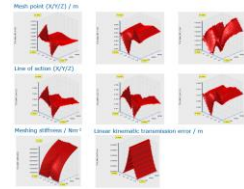
#### Ansol CALYX

- Tooth bending strength**
- EXPORT.DAT:**
  - Time based, local results



#### AVL Python Scripts

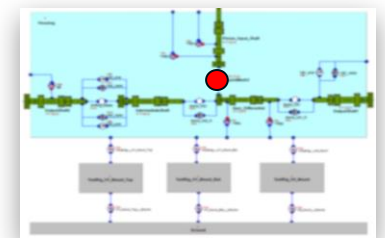
- Post-processing of TCA results:**
  - Analytical lubrication model
  - Flank damage models
- Loaded and kinematic transmission error**
- AVL EXCITE look-up tables**



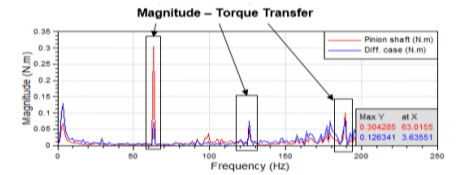
Preselection: Robustness against EPGa

Preselection: Robustness against NVH potential

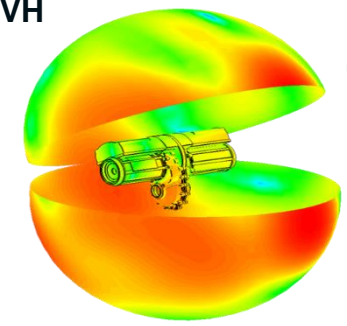
#### AVL EXCITE



#### 1. Dynamic transmission error



#### 2. NVH



# Gear Optimization Workflow

## Micro Geometry

Introduction

Base Variant Analysis

Gear Optimization

Validation

Additional models

**Abaqus FEA**

EPGa

**Unloaded TCA**

.spa  
EPGa

**LTCA**

Look-up  
Tables

**Dynamics**

From base variant:  
• EPGa variation space (load, temperature)

+

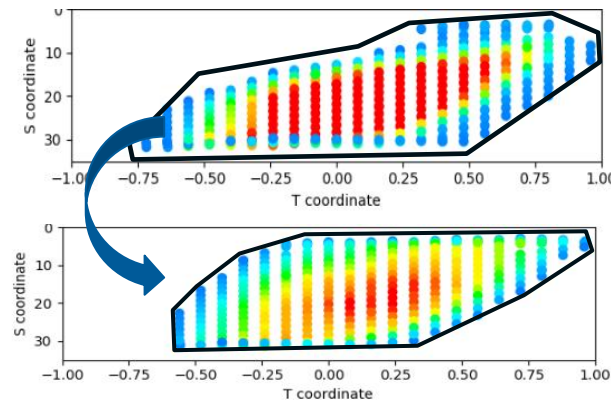
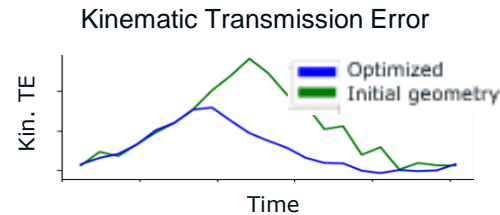
Optimized macro geometry

LTCA results

**3 - 5 variants only**

AVL Python Script / Winkler Mattress Model based TCA

1. Contact pattern and transmission error optimization by applying local flank perturbations



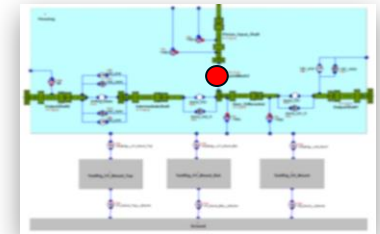
2. Feedback of flank deviation information into GEMS



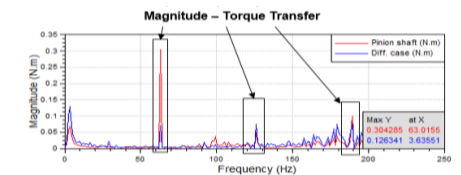
3. Manufacturability guaranteed



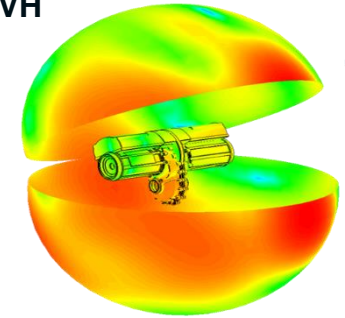
AVL EXCITE



1. Dynamic transmission error



2. NVH





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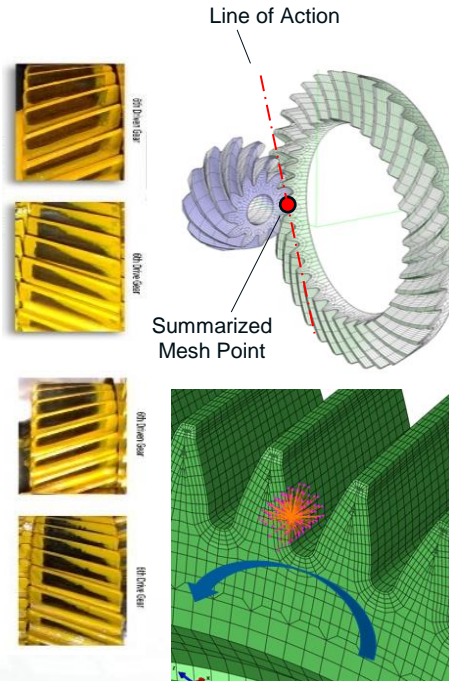
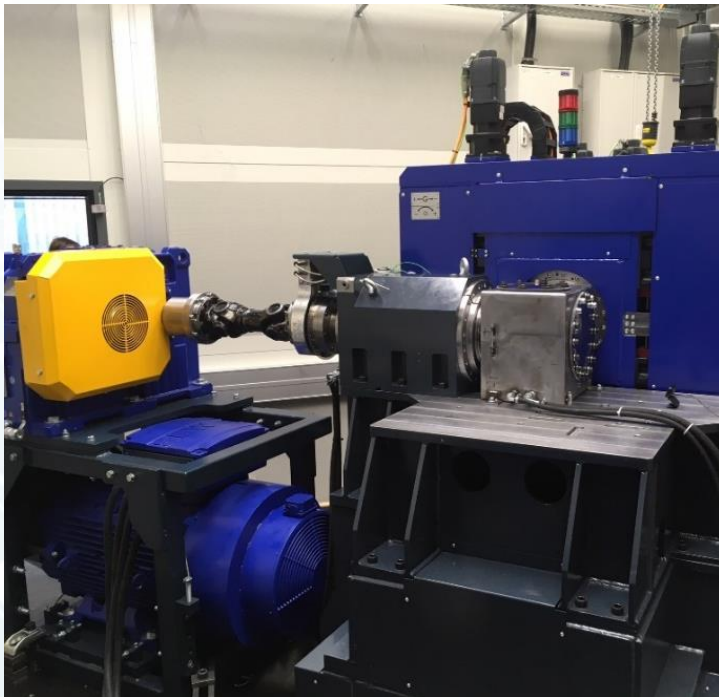
# AVL Validation Test Rig

Introduction

## Hypoid Gear Component Testing

Simulation → Specialized Gear Rig → Validation

Base Variant Analysis



Gear Optimization

Validation

Summary

**Test bed dedicated for model validation by isolating gear pair failures**

## Benefits

<p>Goal: Reduce development time</p>	<ul style="list-style-type: none"> <li>AVL philosophy: Accurate modelling reduces time required in design and prototyping</li> </ul>
<p>Validation</p>	<ul style="list-style-type: none"> <li>Improved control over gear contact control and additional measurements</li> <li>Isolation of gear pair failure modes from axle assembly</li> </ul>
<p>Improved product quality</p>	<ul style="list-style-type: none"> <li>Quality control on component level: NVH, root bending life, surface and subsurface damage, efficiency</li> </ul>

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# Workflow Summary

Introduction

Base Variant Analysis

Gear Optimization

Validation

Summary

## 1. Customer request for optimization

## 2. Base variant analysis

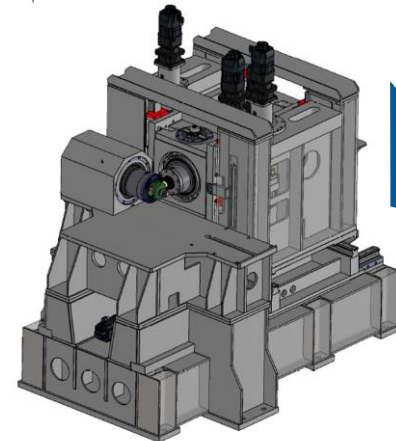
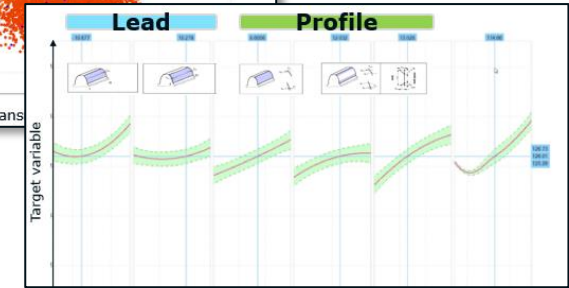
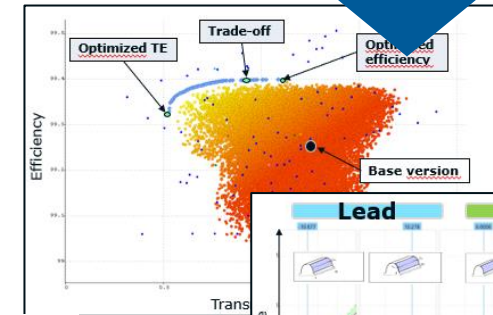
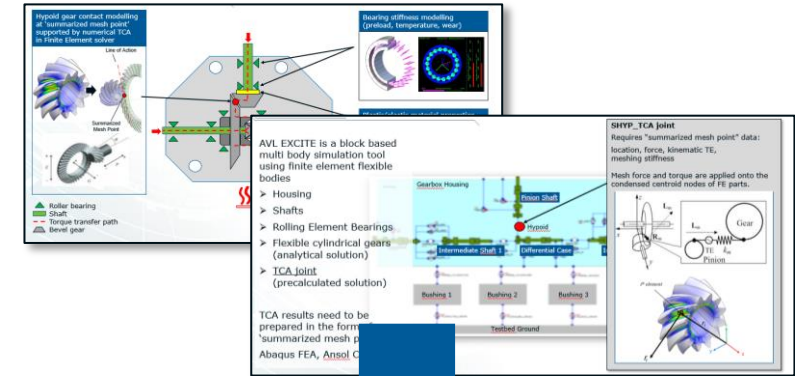
- Input: Initial gear geometry, load spectrum
- Output: EPGa as function of load and temperature

## 3. Optimization by Design of Experiment (DOE)

- Input: Variation of EPGa and gear geometry parameters (+ disturbances)
- Output: Hypersurfaces for target variables; Pareto-optimum; intersection plots

## 4. Model validation

- Isolation of gear pair failure modes
- Controlled environment





# Outlook

Introduction

Base Variant Analysis

Gear Optimization

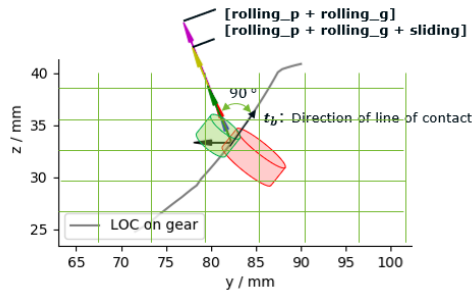
Validation

Summary

## Lubricated Contact Analysis (LLTCA)

*AVL Python Script*

- Analytical EHL formulation
- Surface shear stress
- Thermal stress



## Manufacturing Tolerances

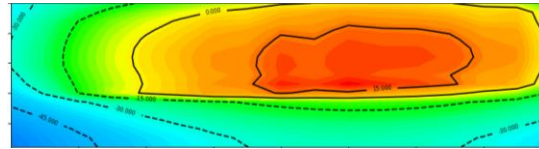
*CALYX LTCA*

- Coordinate Measurement Machine (CMM) results
- Effect on root bending life

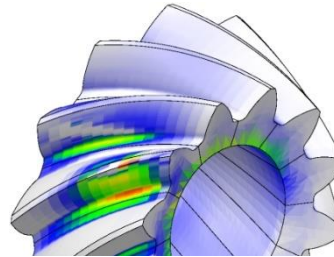
## Surface damage models

*AVL Python Script*

- Fretting / scuffing
- Surface wear



## Loaded TCA

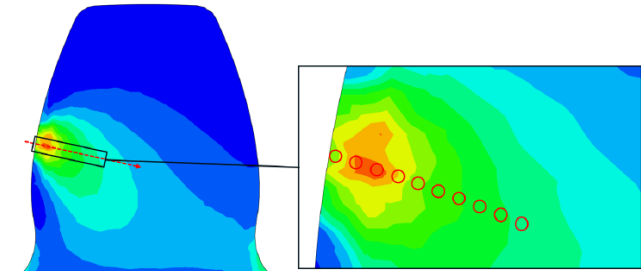


- Tooth bending strength
- Geometrical contact conditions
- Dry contact pressure

## Pitting and Spalling safety

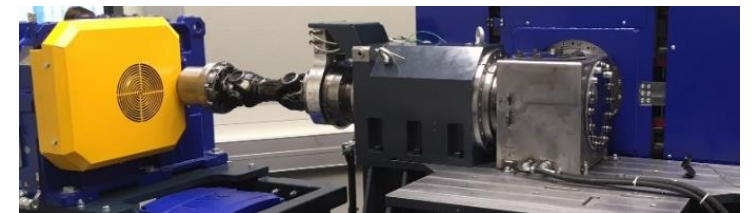
*Abaqus FEA / AVL Python Script*

- Mapped contact conditions from LLTCA
- Enhanced material model
- Subsurface crack initiation life



## Model Validation

*AVL's dedicated specialized gear rig*





Thank You



[www.avl.com](http://www.avl.com)

